

Teaching new tricks to old programs

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Target Data Sciences

May 2017

New vocabularies, not new languages.



The Next 700 Programming Languages

P. J. Landin

Univac Division of Sperry Rand Corp., New York, New York

“... today ... 1,700 special programming languages used to ‘communicate’ in over 700 application areas.”—*Computer Software Issues*, an American Mathematical Association Prospectus, July 1965.

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Can we create fewer new vocabularies as well?

What does it mean?

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$$x + 3 * y$$

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It depends on x and y .

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It depends on $+$, $*$, and 3 :

- *Int, Float, Double*
- $\mathbb{Z}, \mathbb{N}, \mathbb{Q}, \mathbb{R}, \mathbb{C}$

What does it mean?

$$\lambda x y \rightarrow x + 3 * y$$

It depends on $+$, $*$, and 3 :

- *Int, Float, Double*
- $\mathbb{Z}, \mathbb{N}, \mathbb{Q}, \mathbb{R}, \mathbb{C}$
- Vectors
- Polynomials
- Functions
- Regular expressions/languages
- Arbitrary rings, semirings,

Organizing interpretations

- Abstract algebra: interfaces and laws, e.g.,
 - Monoid, group, ring
 - Vector space
 - Functor, applicative, monad, foldable, traversable
 - Category, with products, with coproducts/sums
- Refactor and repurpose proofs and programs. (More with less.)

Example,

$$\text{fold} :: (\text{Foldable } f, \text{Monoid } m) \Rightarrow f\ m \rightarrow m$$

What does it mean?

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- The most basic “operations”: λ , variables, and application.
- We can't re-interpret/overload.

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$$\lambda x y \rightarrow x + 3 * y$$

- The most basic “operations”: λ , variables, and application.
- We can't re-interpret/overload.
- What if there were a way?

Why overload lambda (etc)?

Same benefits as algebraic abstraction:

- Convenient notation.
- Generalized, principled interpretation.
- Modular programming and reasoning.

Why overload lambda?

- Convenient notation for functions.

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- Alternative function implementations:
 - GPU code
 - Circuits
 - Javascript

Why overload lambda?

- Convenient notation for functions.
- Alternative function implementations:
 - GPU code
 - Circuits
 - Javascript
- Enhanced functions:
 - Derivatives and integrals
 - Incremental evaluation
 - Interval analysis
 - Optimization
 - Root-finding
 - Constraint solving

How to overload lambda?

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- Idea: eliminate it, and overload as usual.

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- How?

Eliminating lambda

Introducing lambda

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$const :: b \rightarrow (a \rightarrow b)$

$const\ b = \lambda a \rightarrow b$

$id :: a \rightarrow a$

$id = \lambda a \rightarrow a$

$(\circ) :: (b \rightarrow c) \rightarrow (a \rightarrow b) \rightarrow (a \rightarrow c)$

$g \circ f = \lambda a \rightarrow g (f\ a)$

$(\Delta) :: (a \rightarrow c) \rightarrow (a \rightarrow d) \rightarrow (a \rightarrow c \times d)$

$f \Delta g = \lambda a \rightarrow (f\ a, g\ a)$

$curry :: (a \times b \rightarrow c) \rightarrow (a \rightarrow b \rightarrow c)$

$curry\ f = \lambda a \rightarrow \lambda b \rightarrow f\ (a, b)$

$apply :: (a \rightarrow b) \times a \rightarrow b$

$apply = \lambda(f, a) \rightarrow f\ a$

$= uncurry\ id$

Eliminating lambda

Systematically *un-inline*:

$$(\lambda p \rightarrow k) \quad \dashrightarrow \text{const } k$$

$$(\lambda p \rightarrow p) \quad \dashrightarrow \text{id}$$

$$(\lambda p \rightarrow u \ v) \quad \dashrightarrow \text{apply} \circ ((\lambda p \rightarrow u) \triangle (\lambda p \rightarrow v))$$

$$\begin{aligned} (\lambda p \rightarrow \lambda q \rightarrow u) &\dashrightarrow \text{curry } (\lambda(p, q) \rightarrow u) \\ &\dashrightarrow \text{curry } (\lambda r \rightarrow u [p := \text{fst } r, q := \text{snd } r]) \end{aligned}$$

Automate via a compiler plugin.

Examples

$sqr :: Num\ a \Rightarrow a \rightarrow a$

$sqr\ a = a * a$

$magSqr :: Num\ a \Rightarrow a \times a \rightarrow a$

$magSqr\ (a, b) = sqr\ a + sqr\ b$

$cosSinProd :: Floating\ a \Rightarrow a \times a \rightarrow a \times a$

$cosSinProd\ (x, y) = (cos\ z, sin\ z)$ **where** $z = x * y$

After λ -elimination:

$sqr = mulC \circ (id \triangle id)$

$magSqr = addC \circ (mulC \circ (exl \triangle exl) \triangle mulC \circ (exr \triangle exr))$

$cosSinProd = (cosC \triangle sinC) \circ mulC$

Abstract algebra for functions

Interface:

```
class Category k where  
  id :: a `k` a  
  (o) :: (b `k` c) → (a `k` b) → (a `k` c)  
  infixr 9 o
```

Laws:

$$\begin{aligned} id \circ f &\equiv f \\ g \circ id &\equiv g \\ (h \circ g) \circ f &\equiv h \circ (g \circ f) \end{aligned}$$

Products

Interface:

```
class Category  $k \Rightarrow \text{Cartesian } k$  where  
  type  $a \times_k b$   
   $exl :: (a \times_k b) \rightarrow k \rightarrow a$   
   $exr :: (a \times_k b) \rightarrow k \rightarrow b$   
   $(\Delta) :: (a \rightarrow k \rightarrow c) \rightarrow (a \rightarrow k \rightarrow d) \rightarrow (a \rightarrow k \rightarrow (c \times_k d))$   
  infixr 3  $\Delta$ 
```

Laws:

$$exl \circ (f \Delta g) \equiv f$$

$$exr \circ (f \Delta g) \equiv g$$

$$exl \circ h \Delta exr \circ h \equiv h$$

Coproducts

Dual to product.

```
class Category k  $\Rightarrow$  Cocartesian k where  
  type a  $+_k$  b  
  inl :: a `k` (a  $+_k$  b)  
  inr :: b `k` (a  $+_k$  b)  
  ( $\nabla$ ) :: (a `k` c)  $\rightarrow$  (b `k` c)  $\rightarrow$  ((a  $+_k$  b) `k` c)  
  infixr 2  $\nabla$ 
```

Laws:

$$(f \nabla g) \circ inl \equiv f$$
$$(f \nabla g) \circ inr \equiv g$$
$$h \circ inl \nabla h \circ inr \equiv h$$

Exponentials

First-class “functions” (morphisms):

```
class Cartesian  $k \Rightarrow$  Closed  $k$  where  
  type  $a \Rightarrow_k b$   
  apply     $:: ((a \Rightarrow_k b) \times_k a) \backslash k \backslash b$   
  curry     $:: ((a \times_k b) \backslash k \backslash c) \rightarrow (a \backslash k \backslash (b \Rightarrow_k c))$   
  uncurry   $:: (a \backslash k \backslash (b \Rightarrow_k c)) \rightarrow ((a \times_k b) \backslash k \backslash c)$ 
```

Laws:

$$\begin{aligned} \textit{uncurry} (\textit{curry} f) &\equiv f \\ \textit{curry} (\textit{uncurry} g) &\equiv g \\ \textit{apply} \circ (\textit{curry} f \circ \textit{exl} \triangle \textit{exr}) &\equiv f \\ \textit{apply} &\equiv \textit{uncurry id} \end{aligned}$$

Misc operations

```
class NumCat k a where  
  negateC      :: a `k` a  
  addC, sub, mulC :: (a ×k a) `k` a  
  ...  
...
```

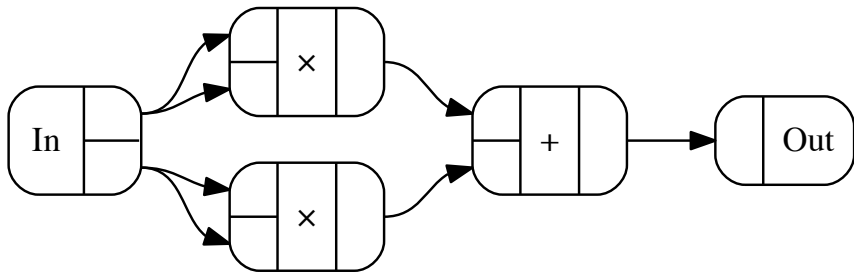

Changing interpretations

- We've eliminated lambdas and variables
- and replaced them with an algebraic vocabulary.
- What happens if we *replace* (\rightarrow) *with other instances?*
(Via compiler plugin.)

Computation graphs — example

$$\text{magSqr}(a, b) = \text{sqr } a + \text{sqr } b$$

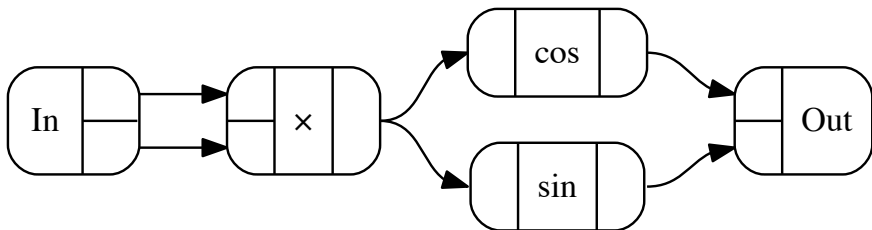
$$\text{magSqr} = \text{addC} \circ (\text{mulC} \circ (\text{exl} \triangle \text{exl}) \triangle \text{mulC} \circ (\text{exr} \triangle \text{exr}))$$



Computation graphs — example

$\text{cosSinProd}(x, y) = (\text{cos } z, \text{sin } z)$ **where** $z = x * y$

$\text{cosSinProd} = (\text{cosC} \Delta \text{sinC}) \circ \text{mulC}$



Computation graphs — example

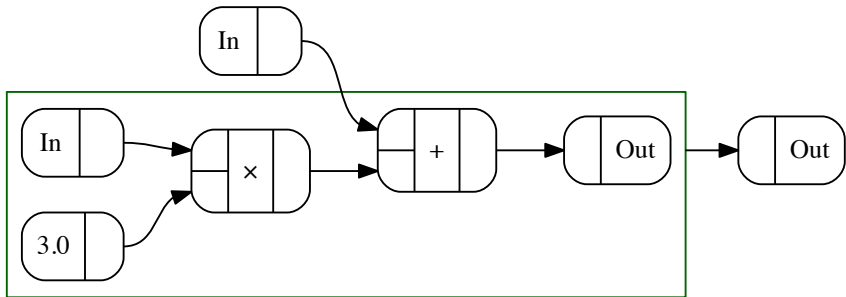
$\lambda x y \rightarrow x + 3 * y$

$\text{curry} (\text{add}C \circ (\text{exl} \triangle \text{mul}C \circ (\text{const } 3.0 \triangle \text{exr})))$

Computation graphs — example

$$\lambda x y \rightarrow x + 3 * y$$

$$\text{curry } (\text{addC} \circ (\text{exl} \triangle \text{mulC} \circ (\text{const } 3.0 \triangle \text{exr})))$$



Computation graphs — implementation sketch

```
newtype Graph a b = Graph (Ports a → GraphM (Ports b))
```

```
type GraphM = State (PortNum, [Comp])
```

```
data Comp = ∀ a b. Comp (Template a b) (Ports a) (Ports b)
```

```
data Template :: * → * → * where
```

```
  Prim      :: String → Template a b
```

```
  Subgraph :: Graph a b → Template () (a → b)
```

```
instance Category Graph where
```

```
  id = Graph return
```

```
  Graph g ∘ Graph f = Graph (g <=< f)
```

```
instance BoolCat Graph where
```

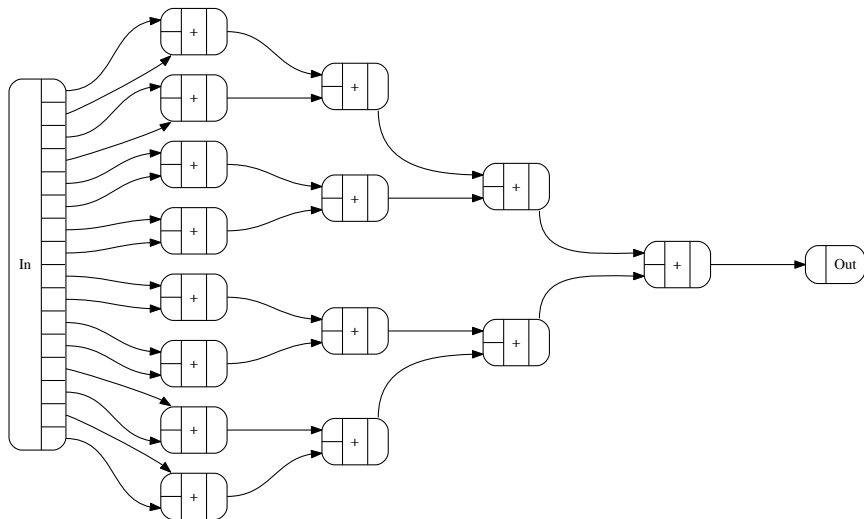
```
  notC = genComp "¬"
```

```
  andC = genComp "∧"
```

```
  orC  = genComp "∨"
```

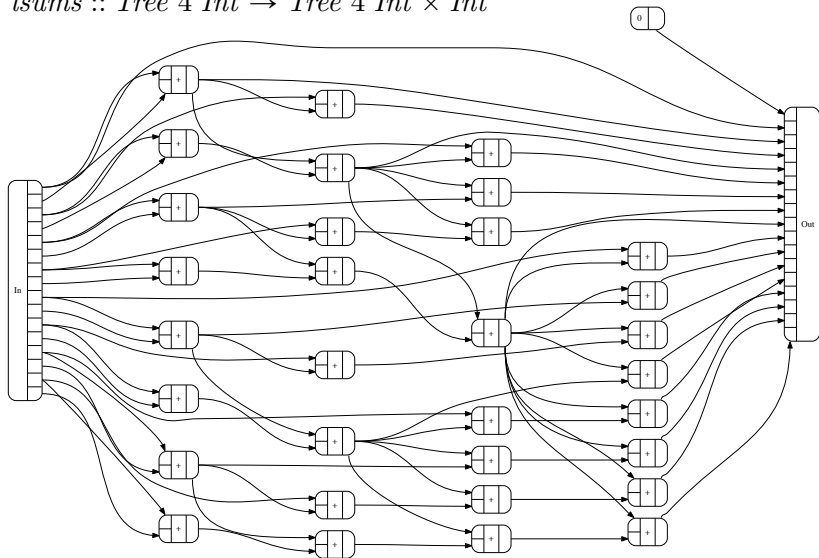
Computation graphs — fold

sum :: Tree 4 Int → Int



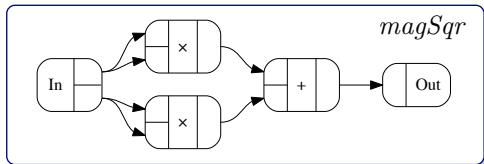
Computation graphs — scan

lsums :: *Tree 4 Int* → *Tree 4 Int* × *Int*



Haskell to hardware

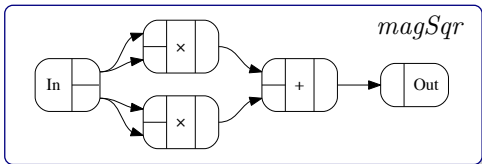
Convert graphs to Verilog:



Haskell to hardware

Convert graphs to Verilog:

```
module magSqr (In_0, In_1, Out);  
  input [31:0] In_0;  
  input [31:0] In_1;  
  output [31:0] Out;  
  wire [31:0] Plus_I0;  
  wire [31:0] Times_I3;  
  wire [31:0] Times_I4;  
  assign Plus_I0 = Times_I3 + Times_I4;  
  assign Out = Plus_I0;  
  assign Times_I3 = In_0 * In_0;  
  assign Times_I4 = In_1 * In_1;  
endmodule
```



Example — graphics

disk :: $\mathbb{R} \rightarrow \text{Region}$

disk *r* *p* = *magSqr* *p* ≤ *sqr* *r*

woob *t* = *disk* (0.75 + 0.25 * *cos* *t*)

type *Region* = $\mathbb{R} \times \mathbb{R} \rightarrow \text{Bool}$

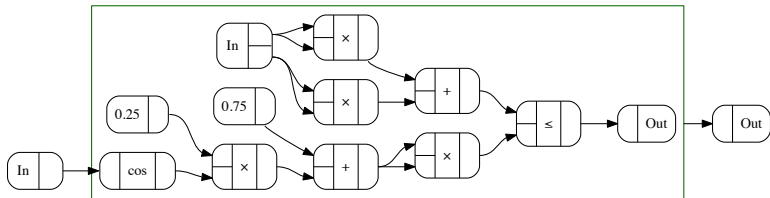
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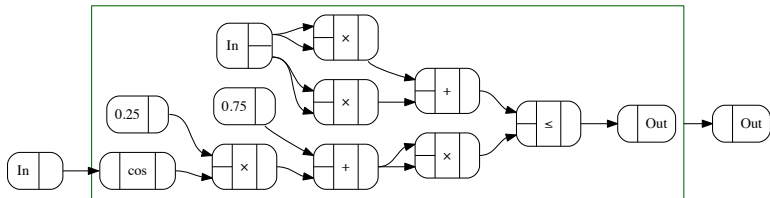
Example — graphics

$disk :: \mathbb{R} \rightarrow Region$

$disk\ r\ p = magSqr\ p \leqslant sqr\ r$

$woob\ t = disk\ (0.75 + 0.25 * cos\ t)$

type $Region = \mathbb{R} \times \mathbb{R} \rightarrow Bool$



```
bool uwoob (float in0, float in1, float in2) // Generated GLSL
{ float v17 = 1.0;
  float v23 = v17 / (0.75 + 0.25 * cos (in0));
  float v24 = in1 * v23;
  float v26 = in2 * v23;
  return v24 * v24 + v26 * v26 <= v17;
}
vec4 effect (vec2 p) { return bw(uwoob(time,p.x,p.y)); }
```

Automatic differentiation

data $D\ a\ b = D\ (a \rightarrow b \times (a \multimap b))$ -- Derivatives are linear maps.

Automatic differentiation

data $D\ a\ b = D\ (a \rightarrow b \times (a \multimap b))$ -- Derivatives are linear maps.

linearD $f = D\ (\lambda a \rightarrow (f\ a, \text{linear}\ f))$

instance *Category* D **where**

$id = \text{linearD}\ id$

$D\ g \circ D\ f = D\ (\lambda a \rightarrow \text{let } \{(b, f') = f\ a; (c, g') = g\ b\} \text{ in } (c, g' \circ f'))$

instance *Cartesian* D **where**

$exl = \text{linearD}\ exl$

$exr = \text{linearD}\ exr$

$D\ f \triangle D\ g = D\ (\lambda a \rightarrow \text{let } \{(b, f') = f\ a; (c, g') = g\ a\} \text{ in } ((b, c), f' \triangle g'))$

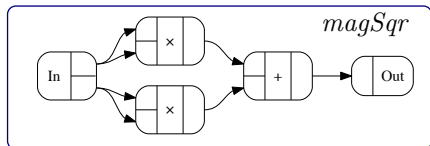
instance *NumCat* D **where**

$\text{negate}C = \text{linearD}\ \text{negate}C$

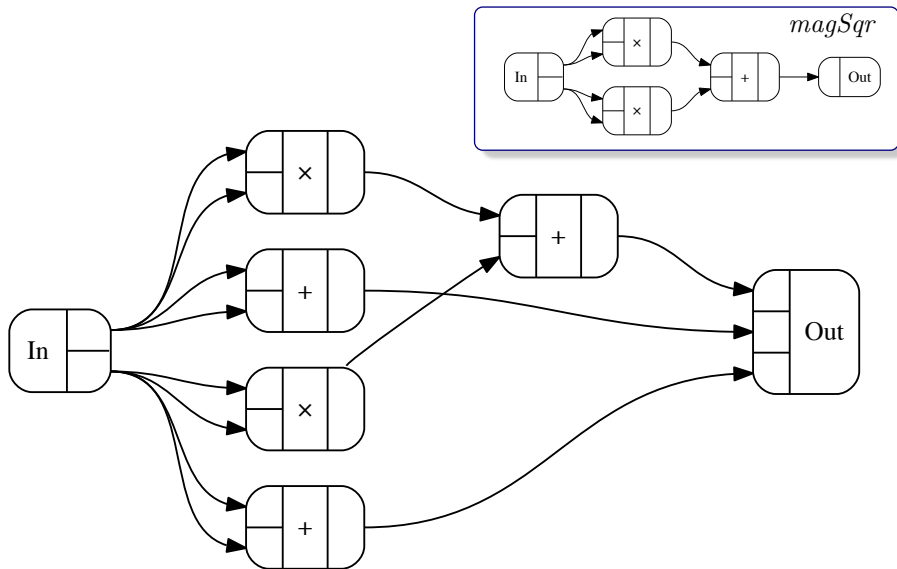
$\text{add}C = \text{linearD}\ \text{add}C$

$\text{mul}C = D\ (\text{mul}C \triangle \lambda(a, b) \rightarrow \text{linear}\ (\lambda(da, db) \rightarrow da * b + db * a))$

Composing interpretations (*Graph* and *D*)

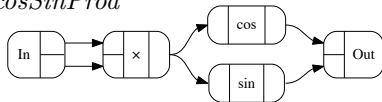


Composing interpretations (*Graph* and *D*)



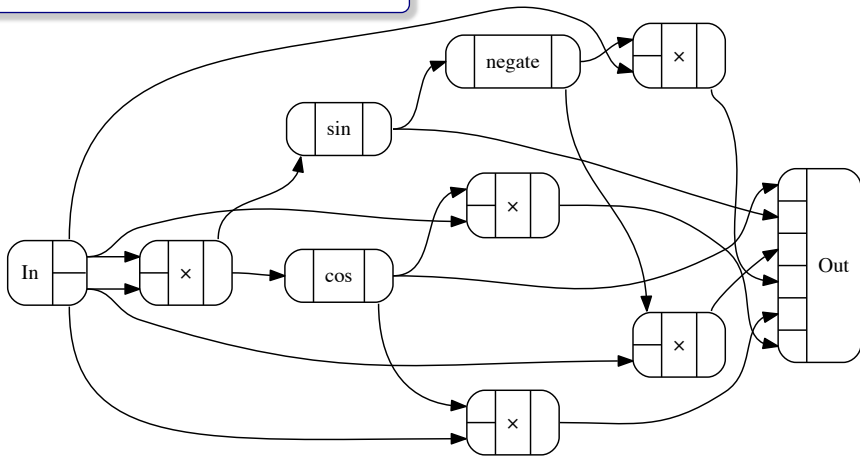
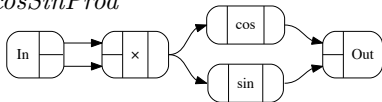
Composing interpretations (*Graph* and *D*)

cosSinProd



Composing interpretations (*Graph* and *D*)

cosSinProd



Interval analysis

data *IFun a b = IFun (Interval a → Interval b)*

Interval analysis

data *IFun* $a\ b = \text{IFun } (\text{Interval } a \rightarrow \text{Interval } b)$

type family *Interval* a

type instance *Interval* *Double* = *Double* \times *Double*

type instance *Interval* $(a \times b) = \text{Interval } a \times \text{Interval } b$

type instance *Interval* $(a \rightarrow b) = \text{Interval } a \rightarrow \text{Interval } b$

instance *Category* *IFun* **where**

id = *IFun id*

IFun g \circ *IFun f* = *IFun (g* \circ *f)*

...

instance *Cartesian* *IFun* **where**

exl = *IFun exl*

exr = *IFun exr*

IFun f \triangle *IFun g* = *IFun (f* \triangle *g)*

Interval analysis

data *IFun* $a\ b = \text{IFun } (Interval\ a \rightarrow Interval\ b)$

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instance *Category* *IFun* **where**

id = *IFun id*

IFun g \circ *IFun f* = *IFun (g \circ *f)**

...

instance *Cartesian* *IFun* **where**

exl = *IFun exl*

exr = *IFun exr*

IFun f \triangle *IFun g* = *IFun (f \triangle *g)**

instance $(Interval\ a \sim (a \times a), Num\ a, Ord\ a) \Rightarrow NumCat\ IFun\ a$ **where**

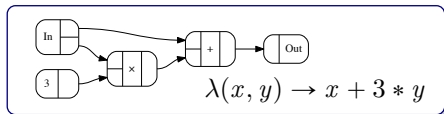
addC = *IFun* $(\lambda((a_{lo}, a_{hi}), (b_{lo}, b_{hi})) \rightarrow (a_{lo} + b_{lo}, a_{hi} + b_{hi}))$

mulC = *IFun* $(\lambda((a_{lo}, a_{hi}), (b_{lo}, b_{hi})) \rightarrow$

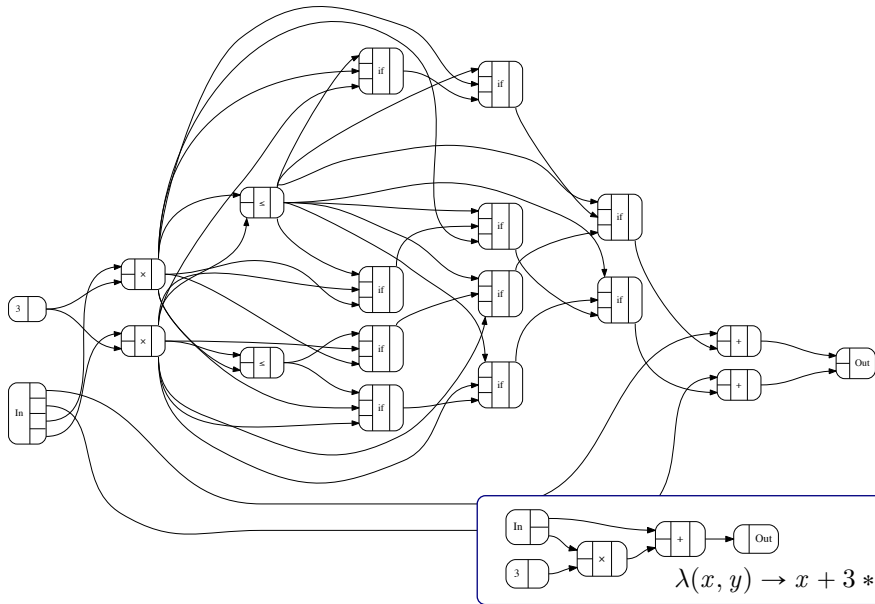
minmax $[a_{lo} * b_{lo}, a_{lo} * b_{hi}, a_{hi} * b_{lo}, a_{hi} * b_{hi}]$

...

Interval analysis — example



Interval analysis — example



Constraint solving (with John Wiegley)

newtype *SMT* *a* *b* = *SMT* (*Kleisli* *Z3* (*E* *a*) (*E* *b*))

data *E* :: * → * **where**

PrimE :: *AST* → *E* *a*

PairE :: *E* *a* → *E* *b* → *E* (*a* × *b*)

instance *Category* *SMT* **where**

id = *SMT* *id*

SMT *g* ∘ *SMT* *f* = *SMT* (*g* ∘ *f*)

instance *Cartesian* *SMT* **where**

exl = *SMT* (*arr* (*exl* ∘ *unpairE*))

exr = *SMT* (*arr* (*exr* ∘ *unpairE*))

SMT *f* △ *SMT* *g* = *SMT* (*arr* *PairE* ∘ (*f* △ *g*))

instance *Num* *a* ⇒ *NumCat* *SMT* *a* **where**

negateC = *liftE*₁ *mkUnaryMinus*

addC = *liftE*₂ *mkAdd*

subC = *liftE*₂ *mkSub*

mulC = *liftE*₂ *mkMul*

Constraint solving (with John Wiegley)

$pred :: (Num\ a, Ord\ a) \Rightarrow a \times a \rightarrow Bool$

$pred\ (x, y) =$

$x < y \wedge$

$y < 100 \wedge$

$0 \leq x - 3 + 7 * y \wedge$

$(x \equiv y \vee y + 20 \equiv x + 30)$

Solution: $(-8, 2)$.

Other examples

- Linear maps
- Incremental evaluation
- Polynomials
- Nondeterministic and probabilistic programming

Domain-specific embedded languages (DSEs)

- *Shallow* (just a library):
 - Great fit with host language.
 - Easy to implement and use.
 - Hard to optimize.
 - Good choice for *expressing ideas*.
- *Deep* (syntactic representation):
 - More room for analysis and optimization.
 - Harder to implement; redundant with host compiler.
 - Less semantic guidance.
 - Syntactically awkward in places.
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 - Good choice for *efficient implementation*.
- *Compiling to categories*:
 - Great fit with host language.
 - Semantic guidance.
 - Easy to implement.
 - Analysis, optimization, non-standard target architectures.

For more details

- The paper *Compiling to categories* (February 2017)

- GitHub project page